# Dislocations and Kirchhoff ellipses 

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## Dislocations

We consider a nonlocal energy

$$
I_{\alpha}(\mu)=\frac{1}{2} \iint_{\mathbb{R}^{2} \times \mathbb{R}^{2}} W_{\alpha}(x-y) d \mu(x) d \mu(y)+\frac{1}{2} \int_{\mathbb{R}^{2}}|x|^{2} d \mu(x)
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W_{\alpha}\left(x_{1}, x_{2}\right)=-\frac{1}{2} \log \left(x_{1}^{2}+x_{2}^{2}\right)+\alpha \frac{x_{1}^{2}}{x_{1}^{2}+x_{2}^{2}}, \quad x=\left(x_{1}, x_{2}\right) \in \mathbb{R}^{2}
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The kernel is obtained by adding to the Coulomb potential an anisotropic term weighted by a parameter $\alpha \in \mathbb{R}$.
$\frac{1}{2} \int_{\mathbb{R}^{2}}|x|^{2} d \mu(x)$ is called the forcing term or confinement. This term produces shear stress or constraint of being in a finite portion of metal

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## Dislocations

## Aim: Characterise the minimiser (equilibrium measure)

■ Does the minimiser exist? Is it compactly supported?
■ Is the minimiser unique?
■ Does the minimiser possess any symmetries?
■ What is the dimension of its support?

- Can we find the minimiser explicitly?


## Some available results

In general one can consider the above problem for a variety of interaction potentials and confinements


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■ Huge literature on existence, confinement, regularity of minimisers for a variety of potentials and for a variety of applications.
(e.g. Cañizo, Carrillo, Castorina, Chipot, Choksi, Delgadino, Fetecau, Figalli, Hittmeir, Hoffmann, Huang, Kolokolnikov, Mainini, Mellet, Patacchini, Simione, Slepčev, Sugiyama, Topaloglu, Volzone, Yao, etc...)

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Explicit computation of the equilibrium measure:

■ only done for the Coulomb kernel and for power laws, and radial external fields

■ based on the Coulomb kernel being the fundamental solution of $\Delta$ and on radial symmetry

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## Some available results

Qualitative study of minimisers of nonlocal interaction energies

- typical assumption is radial symmetry of the potential
- dimensionality of the support for potential with subcritical singularity at 0 (Balagué-Carrillo-Laurent-Raoul)
- symmetrisation techniques (Carrillo-Castorina-Volzone)


## Dislocations: The planar case

Coming back to our dislocation potential

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W_{\alpha}(x)=-\frac{1}{2} \log \left(x_{1}^{2}+x_{2}^{2}\right)+\alpha \frac{x_{1}^{2}}{x_{1}^{2}+x_{2}^{2}}
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When the anisotropy is switched off, namely for $\alpha=0$, the
minimiser is radial, and is given by the circle law $\mu_{0}:=$
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When the anisotropy is switched off, namely for $\alpha=0$, the minimiser is radial, and is given by the circle law $\mu_{0}:=\frac{1}{\pi} \chi_{B_{1}(0)}$, the normalised characteristic function of the unit disc.
(Coulomb gases, random matrices, Fekete sets, Ginibre ensemble; Sandier-Serfaty, Saff-Totik, Frostman, Wigner, Dyson)

## Dislocations: The planar case

## Aim: Characterise the minimiser (equilibrium measure)

■ Does the minimiser exist? Is it compactly supported? YES!
■ Is the minimiser unique? YES!
■ Does the minimiser possess any symmetries? YES! It's radial.
■ What is the dimension of its support? DIM $=2$.
■ Can we find the minimiser explicitly? YES! $\mu_{0}=\frac{1}{\pi} \chi_{B_{1}(0)}$ (circle law).

## Dislocations: The planar case

In the case $\alpha=1$, The minimisers of $I_{1}$ were since long conjectured to be vertical walls of dislocations, and this has been confirmed by [Mora, Rondi, Scardia (2016)]. They proved that the only minimiser of $I_{1}$ is the semi-circle law.

$$
\begin{equation*}
\mu_{1}:=\frac{1}{\pi} \delta_{0} \otimes \sqrt{2-x_{2}^{2}} \mathcal{H}^{1}\llcorner(-\sqrt{2}, \sqrt{2}) \tag{1}
\end{equation*}
$$

on the vertical axis.

## Dislocations: The planar case

It is not difficult to prove that $\mu_{1}$, that is the semicircle law, is the only minimiser of $I_{\alpha}$ for $\alpha \geq 1$, since
$I_{\alpha}\left(\mu_{1}\right)=I_{1}\left(\mu_{1}\right)<I_{1}(\mu) \leq I_{\alpha}(\mu) \forall \mu \neq \mu_{1}$.

The case $\alpha<0$ can be recovered from the knowledge of the case

Can we characterise the minimiser of $I_{\alpha}$ for every $0<\alpha<1$ ?

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Theorem (Carrillo, Mora, M. Rondi, Scardia, Verdera)

Let $0 \leq \alpha<1$. The measure

$$
\begin{equation*}
\mu_{\alpha}:=\frac{1}{\sqrt{1-\alpha^{2}} \pi} \chi_{\Omega(\sqrt{1-\alpha}, \sqrt{1+\alpha})} \tag{2}
\end{equation*}
$$

where
$\Omega(\sqrt{1-\alpha}, \sqrt{1+\alpha}):=\left\{x=\left(x_{1}, x_{2}\right) \in \mathbb{R}^{2}: \frac{x_{1}^{2}}{1-\alpha}+\frac{x_{2}^{2}}{1+\alpha}<1\right\}$,
is the unique minimiser of the functional $I_{\alpha}$ among probability measures $\mathcal{P}\left(\mathbb{R}^{2}\right)$.

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That is, we obtain again the result of [Mora, Rondi, Scardia], but with a different proof based on methods from fluid mechanics and complex analysis
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## The Euler equation in the plane

In 1755 Euler propose the equation for $v(z, t)$, the velocity field of an incompressible and inviscid fluid

$$
(E)\left\{\begin{array}{l}
\partial_{t} v(z, t)+(v \cdot \nabla) v(z, t)=-\nabla p(z, t) \\
\nabla \cdot v=0 \\
v(z, 0)=v_{0}(z)
\end{array}\right.
$$

$$
v \cdot \nabla=v_{1} \partial_{1}+v_{2} \partial_{2}
$$

## The vorticity equation

Taking curl in the 2-D Euler equation we get the vorticity equation also called Helmholtz equation (1858).

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\left\{\begin{array}{l}
\partial_{t} \omega+(v \cdot \nabla) \omega=0 \\
v=\frac{i}{2 \pi} \frac{1}{\bar{z}} * \omega \\
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## Rotating Vortex patches

## Definition

A V-state, also called rotating vortex patch, is a vortex patch that rotates with constant angular velocity. If the initial domain $D_{0}$ has the origin as center of mass, then $D_{t}=e^{i t \Omega} D_{0}$ for a certain angular velocity $\Omega$.

## The two known explicit examples

## Rankine vortex (1858)

If $\Omega=D(0,1)$ is the unit disc, then

$$
\Omega_{t}=D(0,1), \quad 0<t
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$\chi_{D(0,1)}(z)$ is a steady solution to the vorticity equation Kirchhoff vortex (1876)

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$\chi_{D(0,1)}(z)$ is a steady solution to the vorticity equation Kirchhoff vortex (1876)

If $\Omega=\left\{(x, y): x^{2} / a^{2}+y^{2} / b^{2}=1\right\}$ is an ellipse then

$$
\Omega_{t}=e^{i A t} \Omega, \quad 0<t, \quad A=\frac{a b}{(a+b)^{2}}
$$

## Proof of the Theorem

In relation with the existence and uniqueness we have

## Proposition

Let $\alpha \in[0,1]$. Then the energy $I_{\alpha}$ is well defined on $\mathcal{P}\left(\mathbb{R}^{2}\right)$, is strictly convex on the class of measures with compact support and finite interaction energy, and has a unique minimiser in $\mathcal{P}\left(\mathbb{R}^{2}\right)$. Moreover, the minimiser has compact support and finite energy.

In fact the key point for the uniqueness is that the Fourier transform of our kernel never vanishes

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In fact the key point for the uniqueness is that the Fourier transform of our kernel never vanishes

$$
\left\langle\hat{W}_{\alpha}, \varphi\right\rangle=\frac{1}{2 \pi} \int_{\mathbb{R}^{2}} \frac{(1-\alpha) \xi_{1}^{2}+(1+\alpha) \xi_{2}^{2}}{|\xi|^{4}} \varphi(\xi) d \xi
$$

for every $\varphi$ in the Schwarz class.

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To obtain the characterisation of the mimimisers we use that standard computations in potential theory shows that any minimiser $\mu$ of $I_{\alpha}$ must satisfy the following Euler-Lagrange conditions

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\begin{align*}
& \left(W_{\alpha} * \mu_{\alpha}\right)(x)+\frac{|x|^{2}}{2}=C_{\alpha} \quad \text { for every } x \in \Omega(\sqrt{1-\alpha}, \sqrt{1+\alpha})  \tag{3}\\
& \left(W_{\alpha} * \mu_{\alpha}\right)(x)+\frac{|x|^{2}}{2} \geq C_{\alpha} \quad \text { for every } x \in \mathbb{R}^{2}, \tag{4}
\end{align*}
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## Proof of the Theorem

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\begin{aligned}
C_{\alpha} & =2 I_{\alpha}\left(\mu_{\alpha}\right)-\frac{1}{2} \int_{\mathbb{R}^{2}}|x|^{2} d \mu_{\alpha}(x)= \\
& \frac{1}{2}-\log \left(\frac{\sqrt{1-\alpha}+\sqrt{1+\alpha}}{2}\right)+\alpha \frac{\sqrt{1-\alpha}}{\sqrt{1-\alpha}+\sqrt{1+\alpha}}
\end{aligned}
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To prove that the ellipse law $\mu_{\alpha}$ satisfies the Euler-Lagrange conditions, we evaluate explicitly the gradient of the convolution of the kernel $W_{\alpha}$ with the characteristic function of the domain enclosed by a general ellipse

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\begin{aligned}
\nabla\left(W_{\alpha} * \mu_{\alpha}\right)(x)+x=0 & \text { for every } x \in \Omega(\sqrt{1-\alpha}, \sqrt{1+\alpha}), \\
x \cdot \nabla\left(W_{\alpha} * \mu_{\alpha}\right)(x)+|x|^{2} \geq 0 & \text { for every } x \in \mathbb{R}^{2}
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In complex variables the potential $W_{\alpha}$ reads as

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$$

and its gradient
$\nabla W_{\alpha}(x)=-\frac{x}{|x|^{2}}+2 \alpha \frac{x_{1} x_{2}}{|x|^{4}} x^{\perp} \equiv 2 \bar{\partial} W_{\alpha}(z)=-\frac{1}{\bar{z}}+\frac{\alpha}{2} \frac{1}{z}-\frac{\alpha}{2} \frac{z}{\bar{z}^{2}}$,
where $x^{\perp}=\left(x_{2},-x_{1}\right)$.

## Proof of the Theorem

Let $b \geq a>0$ and $\mu_{a, b}:=\frac{1}{\pi a b} \chi_{\Omega(a, b)}$ be the (normalised)
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in order to get $\frac{z}{\bar{z}^{2}} * \chi_{\Omega(a, b)}=\lambda(z-\lambda \bar{z})$ inside $\Omega$

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## Proof of the Theorem

Using the above computations inside and the fact that all the potential are linear inside one obtains

$$
\left\{\begin{array}{l}
-1-\alpha \lambda+a b=0 \\
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To verify the second Euler-Lagrange condition one has to compute all the potentials outside. This computations are much more involved

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## Proof of the Theorem

$V$-states or rotating vortex patches can be viewed as stationary solutions in a reference system that rotates with the patch, and they can be described by means of an equation involving the stream function of the initial patch $D_{0}$

$$
-\log |\cdot| * \chi_{D_{0}}+\Omega|z|^{2}=C, \quad \text { on the boundary of } D_{0},
$$

where $\Omega$ is the angular velocity of the patch and $C$ is a constant.

## Proof of the Theorem

which is formally similar to the first Euler-Lagrange equation

$$
\left(W_{\alpha} * \mu_{\alpha}\right)(x)+\frac{|x|^{2}}{2}=C_{\alpha} \quad \text { for every } x \in \Omega(\sqrt{1-\alpha}, \sqrt{1+\alpha})
$$

## Dislocations: The 3-D case

We consider a nonlocal energy

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I_{\alpha}(\mu)=\frac{1}{2} \iint_{\mathbb{R}^{3} \times \mathbb{R}^{3}} W_{\alpha}(x-y) d \mu(x) d \mu(y)+\frac{1}{2} \int_{\mathbb{R}^{3}}|x|^{2} d \mu(x)
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W_{\alpha}\left(x_{1}, x_{2}, x_{3}\right)=\frac{1}{|x|}+\alpha \frac{x_{1}^{2}}{|x|^{3}}, \quad x=\left(x_{1}, x_{2}, x_{3}\right) \in \mathbb{R}^{3} \tag{7}
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Again the problem is to describe the minimisers of the above energy.

The kernel is obtained by adding to the 3 dimensional Coulomb potential an anisotropic term weighted by a parameter $\alpha \in \mathbb{R}$ In the particular case where $\alpha=0$, the minimiser is radial, and is given by $\mu_{0}:=\frac{3}{1-} \chi_{B_{1}(0)}$, the normalised characteristic function of the unit ball

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## Dislocations: The 3-D case

Again the problem is to describe the minimisers of the above energy.

The kernel is obtained by adding to the 3 dimensional Coulomb potential an anisotropic term weighted by a parameter $\alpha \in \mathbb{R}$.

In the particular case where $\alpha=0$, the minimiser is radial, and is given by $\mu_{0}:=\frac{3}{4 \pi} \chi_{B_{1}(0)}$, the normalised characteristic function of the unit ball.

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## Theorem

Let $-1<\alpha<1$. There exist constants $a(\alpha)$ and $b(\alpha)$ such that the measure

$$
\begin{equation*}
\mu_{\alpha}:=\frac{3}{a b^{2} 4 \pi} \chi_{\Omega(a, b, b)}, \tag{8}
\end{equation*}
$$

where

$$
\Omega(a, b, b):=\left\{x=\left(x_{1}, x_{2}, x_{3}\right) \in \mathbb{R}^{3}: \frac{x_{1}^{2}}{a^{2}}+\frac{x_{2}^{2}}{b^{2}}+\frac{x_{3}^{2}}{b^{2}}<1\right\}
$$

is the unique minimiser of the functional $I_{\alpha}$ among probability measures $\mathcal{P}\left(\mathbb{R}^{3}\right)$.

## Dislocations: 3D

The minimizer is given by the probability measure of the characteristic functions of an oblate ellipsoid ( $0<\alpha<1$ ), the characteristic function of a ball $(\alpha=0)$ or the characteristic function of a prolate ellipsoid $(-1<\alpha<0)$.

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$$
\begin{array}{ll}
\left(W_{\alpha} * \mu_{\alpha}\right)(x)+\frac{|x|^{2}}{2}=C_{\alpha} & \text { for every } x \in \Omega(a, b, b) \\
\left(W_{\alpha} * \mu_{\alpha}\right)(x)+\frac{|x|^{2}}{2} \geq C_{\alpha} \quad \text { for every } x \in \mathbb{R}^{3} \tag{10}
\end{array}
$$

## Dislocations: 3D

To do that, one has to compute explicitly the kernel associated to this energy inside and outside our ellipsoid.

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## Open problems

We would like to consider the problem of dislocations using the Coulomb potentials, the same confinement, but replacing the anisotropic term.

For instance, let's consider the nonlocal energy
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defined on probability measures $\mu \in \mathcal{P}\left(\mathbb{R}^{2}\right)$, where the interaction potential $W_{\alpha}$ is given by
$W_{\alpha}\left(x_{1}, x_{2}\right)=-\frac{1}{2} \log \left(x_{1}^{2}+x_{2}^{2}\right)+\alpha \frac{x_{1}^{4}}{\left(x_{1}^{2}+x_{2}^{2}\right)^{2}}, \quad x=\left(x_{1}, x_{2}\right) \in \mathbb{R}^{2}$.

## Open problems

In general we can consider an anisotropic case being

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\frac{x_{1}^{2 n}}{\left(x_{1}^{2}+x_{2}^{2}\right)^{n}}
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## For $n=2$ the candidates are a family of ellipses.

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## Thank you for your attention


[^0]:    and its gradient

