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Statistical study of spatial dependences in long memory random fields on a lattice, point processes and random geometry.

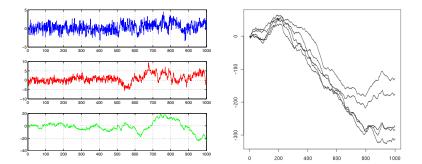
Frédéric Lavancier, Laboratoire de Mathématiques Jean Leray, Nantes

9 décembre 2011.

Introduction

Point processes, random geometry

Long memory, self-similarity in (multivariate) time series :



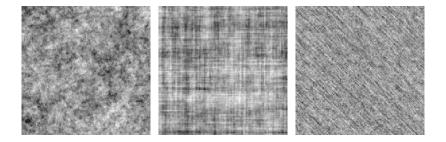
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Introduction

Point processes, random geometry

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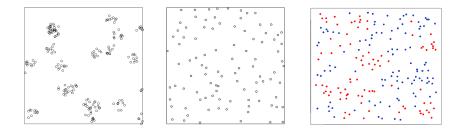
Long memory, self-similarity in images :



Introduction

Point processes, random geometry

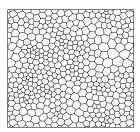
Attraction, repulsion between points :

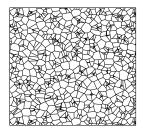


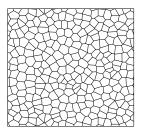
Introduction

Point processes, random geometry

Dependence between cells of a tesselation :





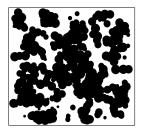


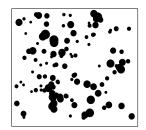
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Introduction

Point processes, random geometry

Random sets as a union of interacting balls :







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Point processes, random geometry

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Introduction

General motivations

Developping mathematical models that

- respect some prescribed features (e.g. self-similiarity, long range dependence, repulsion or attraction between points,...);
- are flexible enough (through few parameters);
- we can simulate.

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Introduction

General motivations

Developping mathematical models that

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- we can simulate.

From a stastical point of view :

- fitting these models to data (inference problem);
- assessing the theoretical quality of inference (consistency, limiting law, optimality,...);
- providing some diagnostic tools :
 - adequation of the model to data,
 - change-point problems.

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1 Self-similarity, Long memory

- Vector Fractional Brownian Motion
- Long memory time series
- Long memory random fields (images)

2 Point processes, random geometry

- Estimation of Gibbs point processes
- Model validation for Gibbs point processes

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Self-similarity, Long memory

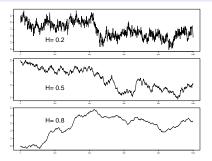
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Point processes, random geometry

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Fractional Brownian Motion

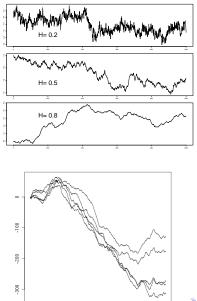
Some univariate examples :



Point processes, random geometry

Fractional Brownian Motion

Some univariate examples :



 \rightarrow Vector (or Multivariate) FBM

Point processes, random geometry

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Vector FBM with P.-O. Amblard, J.-F. Coeurjolly, A. Philippe, D. Surgailis

A multivariate process $\mathbf{B}(t) = (B_1(t), \dots, B_p(t))$ is a Vector FBM with parameter $\mathbf{H} = (H_1, \dots, H_p)$ if $\mathbf{B}(0) = 0$ and

- it is Gaussian;
- it is **H**-self-similar, i.e.

$$\forall c > 0, \ (B_1(ct), \dots, B_p(ct))_{t \in \mathbb{R}} \stackrel{\mathcal{L}}{=} (c^{H_1} B_1(t), \dots, c^{H_p} B_p(t))_{t \in \mathbb{R}};$$

• it has stationary increments.

Point processes, random geometry

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• it has stationary increments.

Lamperti type result :

If there exist a vector process $(Y_1(t), \ldots, Y_p(t))_{t \in \mathbb{R}}$ and real functions a_1, \ldots, a_p such that

$$(a_1(n)Y_1(nt),\ldots,a_p(n)Y_p(nt)) \xrightarrow[fidi]{n \to \infty} \mathbf{Z}(t),$$

then the vector process $(\mathbf{Z}(t))$ is self-similar.

Convergence of partial sums :

Any Vector FBM can be obtained as the limit of partial sums of some superlinear processes.

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Comprehensive characterisation : (p = 2)

- **1.** Let $(B_1(t), B_2(t))$ be a (H_1, H_2) -VFBM, then (when $H_1 + H_2 \neq 1$) :
 - B_1 is a H_1 -FBM and B_2 is a H_2 -FBM
 - for $0 \le s \le t$, the cross-covariance is

 $\mathbb{E}B_1(s)B_2(t) \propto (\rho+\eta)s^{H_1+H_2} + (\rho-\eta)t^{H_1+H_2} - (\rho-\eta)(t-s)^{H_1+H_2}$ with $\rho = \operatorname{corr}(B_1(1), B_2(1)), \ \eta = \frac{\operatorname{corr}(B_1(1), B_2(-1)) - \operatorname{corr}(B_1(-1), B_2(1))}{2-2^{H_1+H_2}}.$

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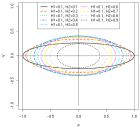
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2. Conversely any Gaussian process with the above covariance function is a VFBM iff for some known R > 0

$$\rho^2 \sin\left(\frac{\pi}{2}(H_1 + H_2)\right)^2 + \eta^2 \cos\left(\frac{\pi}{2}(H_1 + H_2)\right)^2 \le R$$

 \rightarrow not possible to set up arbitrary correlated FBM



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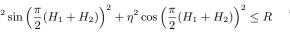
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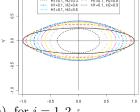
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3. Consider the increments $\Delta B_i(n) = B_i(n+1) - B_i(n)$, for i = 1, 2.

Comprehensive characterisation : (p = 2)

- **1.** Let $(B_1(t), B_2(t))$ be a (H_1, H_2) -VFBM, then (when $H_1 + H_2 \neq 1$):
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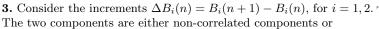
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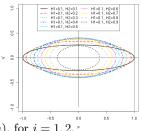
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 \rightarrow not possible to set up arbitrary correlated FBM



$$\mathbb{E}\Delta B_1(n)\Delta B_2(n+h) \sim \kappa |h|^{H_1+H_2-2}$$

→ Very constrained cross-correlation (For instance $H_1 + H_2 \ge 1 \Rightarrow$ long-range cross-dependence)

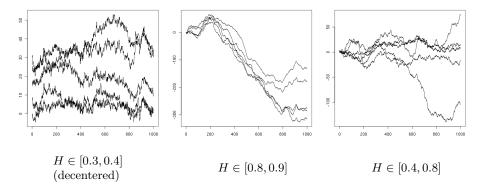


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Some examples :

Simulations are achieved thanks to a Wood and Chan algorithm.

Below, the correlation between any couple of FBM is $\rho = 0.6$



Point processes, random geometry

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Self-similarity, Long memory

- Vector Fractional Brownian Motion
- Long memory time series
- Long memory random fields (images)

Point processes, random geometry

Definition :

A stationary, L^2 , time series $(X(n))_{n \in \mathbb{Z}}$ exhibits long memory if

$$\sum_{n \in \mathbb{Z}} |r(n)| = +\infty$$

where r denotes the covariance function of X.

Typically : for some 0 < d < 0.5, $r(n) \sim_{\infty} \kappa |n|^{2d-1}$. The parameter d is called the *long memory parameter*.

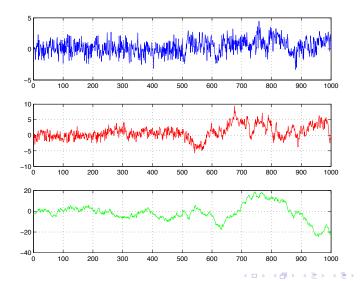
• If B is a FBM, X(n) = B(n+1) - B(n) with d = H - 0.5.

• An
$$I(d)$$
 time series : $X(n) = (1-L)^{-d} \epsilon(n)$
(where ϵ is a white noise and L the lag operator : $L\epsilon_n = \epsilon_{n-1}$)

Point processes, random geometry

$Change \ point \ problem \ {}_{\rm with \ R. \ Leipus, \ A. \ Philippe, \ D. \ Surgailis}$

Constant vs non-constant long memory parameter? $\underline{ex} : I(d_1) \to I(d_2)$



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Point processes, random geometry

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Change point problem with R. Leipus, A. Philippe, D. Surgailis

Basically, under
$$\mathbf{H}_0 : \underline{d} \text{ is constant} :$$

 $n^{-d-0.5} \sum_{k=1}^{[nt]} X(k) \xrightarrow{\mathcal{D}([0,1])} \kappa B_{d+0.5}(t) \text{ and } Var\left(\sum_{k=1}^{[nt]} X(k)\right) \approx n^{2d+1}$

Under \mathbf{H}_1 : <u>*d* increases</u>, for some t_0

$$Var\left(\sum_{k=1}^{[nt_0]} X(k)\right) \ll Var\left(\sum_{k=[nt_0]}^n X(k)\right)$$

 \Rightarrow To test for \mathbf{H}_0 against \mathbf{H}_1 , we estimate and compare these variances.

Point processes, random geometry

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Let
$$S_j = \sum_{k=1}^j X(k)$$
 and $S_{n-j}^* = \sum_{k=j+1}^n X(k)$. Define

- the forward variance : $V_k = \widehat{Var}(S_1, \dots, S_k)$
- the backward variance : $V_{n-k}^* = \widehat{Var}(S_{n-k+1}^*, \dots, S_1^*)$

Test statistic, Consistency

$$I_n = \int_0^1 \frac{V_{n-[nt]}^*}{V_{[nt]}} \mathrm{d}t$$

Under $\mathbf{H}_0 : I_n \to I(B_{d+0.5})$ (simulable); Under $\mathbf{H}_1 : I_n \to +\infty$

Point processes, random geometry

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Self-similarity, Long memory

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Point processes, random geometry

Definition :

A stationary, L^2 , random field $(X(n))_{n \in \mathbb{Z}^d}$ exhibits long memory if

$$\sum_{n\in\mathbb{Z}^d}|r(n)|=+\infty$$

where r denotes the covariance function of X.

Main difference with time series : possible occurrence of anisotropy.

Examples
$$(d = 2)$$
: for $0 < \alpha < 1$
 $r(n_1, n_2) \sim_{\infty} (n_1^2 + n_2^2)^{-\alpha}$ $r(n_1, n_2) \sim_{\infty} |n_1|^{-\alpha} |n_2|^{-\alpha}$ $r(n_1, n_2) \sim_{\infty} |n_1 + n_2|^{-\alpha}$
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Point processes, random geometry

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Investigations on long memory random fields

 ${\bf Modelling}: {\rm long} \ {\rm memory} \ {\rm random} \ {\rm fields} \ {\rm appear}$

- in similar models as for time series (increment of fractional Brownian sheet; aggregation of short memory random fields; fractional filtering of a white noise)
- in some Gibbs processes on \mathbb{Z}^d in phase transition ex : Ising model at the critical temperature

Point processes, random geometry

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Limit theorems, statistical applications :

- for partial sums → non Central Limit Theorems
 ⇒ Testing for the presence of long memory.
- for the empirical process \longrightarrow asymptotic degeneracy \Rightarrow Asymptotics for U-Statistics.
- for some quadratic forms (with A. Philippe) \longrightarrow non-CLTs for $\sum g(i-j)X(i)X(j)$ where $(X(i))_{i\in\mathbb{Z}^2}$ is Gaussian.
 - \Rightarrow Asymptotics of empirical covariance functions.

Self-similarity, Long memory ○○○○○○○○○○

Point processes, random geometry

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Partial sums of long memory random fields

Let $X(n) = \sum_{k \in \mathbb{Z}^d} a_k \epsilon(n-k)$, where $(a_k) \in \ell^2$ and ϵ is a Gaussian white noise.

Theorem

Denote $a(x) = \sum_{k \in \mathbb{Z}^d} a_k e^{i k \cdot x}$. If $a \in L^2$ and $\forall \lambda$, $a(\lambda x) = |\lambda|^{-\alpha} a(x)$, $0 < \alpha < d$, then denoting $A_n = \{1, \ldots, n\}^d$

$$\frac{1}{n^{d/2+\alpha}} \sum_{k \in A_{[nt]}} X_k \xrightarrow{\mathcal{D}([0,1]^d)} \int_{\mathbb{R}^d} a(x) \prod_{j=1}^d \frac{\mathrm{e}^{it_j x_j} - 1}{ix_j} \mathrm{d}Z(x)$$

The limit is the Fractional Brownian Sheet only when $a(x) = \prod_{i=1}^{d} |x_i|^{-H_i}$.

Self-similarity, Long memory ○○○○○○○○○○

Point processes, random geometry

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$$\frac{1}{n^{d/2+\alpha}} \sum_{k \in A_n} X_k = \frac{1}{n^{d/2+\alpha}} \sum_{k \in A_n} \int_{[-\pi,\pi]^d} a(x) \mathrm{e}^{i\,k.x} \mathrm{d}Z(x) \quad Z : \text{spectral measure of } \epsilon$$
$$= \int_{[-\pi,\pi]^d} n^{-\alpha} a(x) \sum_{k \in A_n} \mathrm{e}^{i\,k.x} \frac{\mathrm{d}Z(x)}{n^{d/2}}$$
$$= \int_{[-n\pi,n\pi]^d} a(x) \prod_{j=1}^d \frac{\mathrm{e}^{ix_j} - 1}{n(\mathrm{e}^{ix_j/n} - 1)} \mathrm{d}Z(x) \xrightarrow{L^2} \int_{\mathbb{R}^d} a(x) \prod_{j=1}^d \frac{\mathrm{e}^{ix_j} - 1}{ix_j} \mathrm{d}Z(x)$$

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2 Point processes, random geometry

- Estimation of Gibbs point processes
- Model validation for Gibbs point processes

Point processes, random geometry

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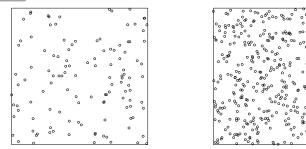
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Point processes

Notation :

- Denote by φ a point pattern on \mathbb{R}^d , i.e. $\varphi = \bigcup_{i \in \mathcal{I}} x_i$, for $\mathcal{I} \subset \mathbb{N}^*$
- A point process Φ is a random variable on the space $\Omega = \{\varphi\}$.

Example : the Poisson point process \rightarrow independance in locations



How to introduce dependencies between the location of points?

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Gibbs point processes (basic definition)

They are absolutely continuous w.r.t the Poisson point process with density

$$f_{\theta}(\varphi) = \frac{1}{c_{\theta}} e^{-V_{\theta}(\varphi)}, \quad \text{for some parameter } \theta \in \mathbb{R}^{p}.$$

 $V_{\theta}(\varphi)$: energy of φ also called Hamiltonian (belongs to $\mathbb{R} \cup \{+\infty\}$)

- φ is more likely to occur if $V_{\theta}(\varphi)$ is small.
- if $V_{\theta}(\varphi) = +\infty$, then φ is forbidden.

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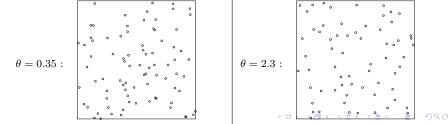
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- φ is more likely to occur if $V_{\theta}(\varphi)$ is small.
- if $V_{\theta}(\varphi) = +\infty$, then φ is forbidden.

Example : Strauss process with range of interaction R = 0.05 on $[0, 1]^2$

$$V_{\theta}(\varphi) = \theta \sum_{(x,y) \in \varphi} \mathbb{1}_{|y-x| < R}, \quad \theta > 0$$



Geometric interactions

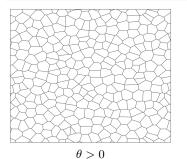
Point processes, random geometry 0000000000

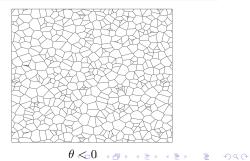
Geometric interactions

For a point pattern φ , denote $Vor(\varphi)$ the associated Voronoï tessellation.

Gibbs Voronoï tessellation : one example

$$V_{\theta}(\varphi) = \sum_{C \in \operatorname{Vor}(\varphi)} V_1(C) + \left. \begin{array}{l} \theta \sum_{\substack{C, C' \in \operatorname{Vor}(\varphi) \\ C \text{ and } C' \text{ are neighbors}}} \left| vol(C) - vol(C') \right| \\ V_1(C) = \begin{cases} +\infty & \text{if the cell is too "irregular",} \\ 0 & \text{otherwise} \end{cases} \right.$$





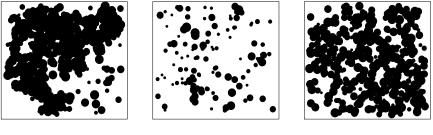
Geometric interactions

Quermass model

Each point $x \in \varphi$ is associated with a random radius r.

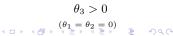
$$V_{\theta}(\varphi) = \theta_1 \ \mathcal{P}(\Gamma) + \theta_2 \ \mathcal{A}(\Gamma) + \theta_3 \ \mathcal{E}(\Gamma) \quad \text{where} \quad \Gamma = \bigcup_{x \in \varphi} B(x, r)$$

 \mathcal{P} : perimeter \mathcal{A} : area \mathcal{E} : EP characteristic (nb connected sets - nb holes).



 $\theta_1 > 0$ $(\theta_2 = \theta_3 = 0)$

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Statistical issues

Let φ be a point pattern observed (or Vor(φ), or Γ ,...) on a domain Λ .

Assumption : φ is the realisation of a Gibbs point process associated to V_{θ} for some (unknown) $\theta \in \mathbb{R}^{p}$.

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The family $(V_{\theta})_{\theta}$ must lead to a well defined Gibbs process for all θ (For the geometric interactions above, see D. Dereudre, R. Drouilhet, H.-O. Georgii)

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1 How to estimate θ ?

From $f_{\theta}(\varphi) = \frac{1}{c_{\theta}} e^{-V_{\theta}(\varphi)}$: maximum likelihood procedure.

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2 Is the above assumption reasonable?

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Takacs-Fiksel method

Campbell equilibrium equation (Georgii, Nguyen, Zessin)

Let $V_{\theta}(x|\varphi) = V_{\theta}(\varphi \cup x) - V_{\theta}(\varphi)$ (energy needed to insert x in φ) Φ is a Gibbs point process with energy V_{θ} if and only if, for all function h,

$$\mathbb{E}_{\Phi}\left(\int_{\mathbb{R}^d} h\left(x,\Phi\right) \mathrm{e}^{-V_{\theta}\left(x|\Phi\right)} \mathrm{d}x\right) = \mathbb{E}_{\Phi}\left(\sum_{x\in\Phi} h\left(x,\Phi\setminus x\right)\right)$$

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Empirical counterpart : Takacs Fiksel estimation Let h_1, \ldots, h_k be K test functions (to be chosen),

$$\hat{\theta} = \arg\min_{\theta} \sum_{k=1}^{K} \left[\int_{\Lambda} h_k(x, \varphi) \mathrm{e}^{-V_{\theta}(x|\varphi)} \mathrm{d}x - \sum_{x \in \varphi} h_k(x, \varphi \setminus x) \right]^2.$$

TF estimation includes pseudo-likelihood estimation as a particular case

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TF estimation includes pseudo-likelihood estimation as a particular case

Contributions : with J.-F. Coeurjolly, D. Dereudre, R. Drouihet, K. Stankova-Helisova

- Identifiability $(K > dim(\theta))$, consistency, asymptotic normality;
- Extension to a two-step procedure in presence of (possible non-hereditary) hardcore interactions;
- Application to Gibbs Voronoï tessellations;
- Application to Quermass model, where points are not observed.

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 $Model \ Validation \ {}_{\rm with \ J.-F. \ Coeurjolly}$

Let φ a point pattern supposed to be the observation on Λ of a Gibbs process with parametric potential V_{θ} . Let $\hat{\theta}$ be an estimate of θ from φ .

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Let φ a point pattern supposed to be the observation on Λ of a Gibbs process with parametric potential V_{θ} . Let $\hat{\theta}$ be an estimate of θ from φ .

The residuals assess the Campbell equilibrium : for any h,

$$R_{\Lambda}(h) = |\Lambda|^{-1} \left(\int_{\Lambda} h(x,\varphi) \mathrm{e}^{-V_{\widehat{\theta}}(x|\varphi)} \mathrm{d}x - \sum_{x \in \varphi} h(x,\varphi \setminus x) \right).$$

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If the model is well specified, we expect, for any h, $R_{\Lambda}(h) \approx 0$. We have proved : as $\Lambda \to \mathbb{R}^d$, $R_{\Lambda}(h) \to 0$ and $R_{\Lambda}(h) \sim \mathcal{N}(0, \Sigma)$.

Towards χ^2 goodness of fit tests : 2 frameworks

$\begin{cases} R_{\Lambda}(h_1) \\ \vdots \\ R_{\Lambda}(h_j) \\ \vdots \\ R_{\Lambda}(h_s) \end{cases}$

$R_{\Lambda_1}(h)$	$R_{\Lambda_2}(h)$	
		$R_{\Lambda_q}(h)$

 $\sum_{j=1}^{s} R_{\Lambda}(\varphi, h_{j})^{2} \sim \chi^{2} \qquad \qquad \sum_{j=1}^{q} R_{\Lambda_{j}}(\varphi, h)^{2} \sim \chi^{2} \quad \qquad \exists \qquad \Im \triangleleft \heartsuit$

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Theoretical Ingredients

For the estimation and the validation procedures, our asymptotic results rely on

- the Campbell equilibrium equation,
- an ergodic theorem (Nguyen and Zessin),
- the central limit theorem below.

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CLT for a linear functional $U(\Phi_{\Lambda})$ where $\Phi_{\Lambda} = \Phi \cap \Lambda$

Assume that if $\Lambda = \bigcup_{k=1}^{n} \Delta_k$ for disjoint Δ_k 's then $U(\Phi_{\Lambda}) = \sum_{k=1}^{n} U(\Phi_{\Delta_k})$ Basically, if

(i) Conditioned centering : $\mathbb{E}\left[U(\Phi_{\Delta_k})|\Phi_{\Delta_j}, j \neq k\right] = 0$

 $\left(ii\right)$ Convergence of empirical covariances :

$$\frac{1}{n} \sum_{k=1}^{n} \sum_{k'=1}^{n} U(\Phi_{\Delta_k}) U(\Phi_{\Delta_{k'}}) \xrightarrow{L^1} \Sigma$$

then
$$\frac{1}{\sqrt{n}} \sum_{k=1}^{n} U(\Phi_{\Delta_k}) \xrightarrow{\mathcal{L}} \mathcal{N}(0, \Sigma)$$

The key assumption (i) allows us to go without mixing assumptions (which typically do not hold for all values of θ for a Gibbs process).

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Alternatives to Gibbs point processes?

Gibbs processes introduce interactions in a very natural way, but

- they can be tedious to simulate
- there are many remaining challenges for inference

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Alternatives to Gibbs processes :

• Cox processes : Poisson processes with random intensity function. ⇒ They induce clustered point patterns.

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Alternatives to Gibbs processes :

- Cox processes : Poisson processes with random intensity function. ⇒ They induce clustered point patterns.
- Determinantal point processes (with J. Møller and E. Rubak) Their joint intensities depend on a covariance function C.

 \Rightarrow They are repulsive point processes, for $g(h) = 1 - \frac{C(h)^2}{C(0)^2}$.

Appeals :

- \triangleright Perfect and fast simulation is available
- $\,\triangleright\,$ Flexible models : just consider a parametric family of covariance functions
- Inference is feasible by standard methods (maximum likelihood, contrast functions,...)

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Thank you.