Schémas numériques pour l'équation de Vlasov collisionnelle en régime de rayon de Larmor fini

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Context

- Consider a 3Dx-3Dv collisional Vlasov equation in the finite Larmor radius regime.
- Model and asymptotics studied by Bostan and Finot[3].
- Our contribution: multiscale schemes with asymptotic properties.

[3] M. Bostan, A. Finot, *Communications in Contemporary Mathematics*, 2019

Outline

Presentation of the model

We consider the collisional Vlasov equation

$$\partial_t f + v \cdot \nabla_x f + (E + v \times B) \cdot \nabla_v f = \frac{1}{\tau} Q[f]$$

with

- $(t, x, v) \in \mathbb{R}_+ \times \mathbb{R}^3 \times \mathbb{R}^3$ the time, space and velocity variables,
- $f(t, x, v) : \mathbb{R}_+ \times \mathbb{R}^3 \times \mathbb{R}^3 \to \mathbb{R}$ the particle distribution function,
- $E(t, x) : \mathbb{R}_+ \times \mathbb{R}^3 \to \mathbb{R}^3$ and $B(t, x) : \mathbb{R}_+ \times \mathbb{R}^3 \to \mathbb{R}^3$ external electric and magnetic fields.

Presentation of the model - collision term

- $Q[f]$ the BGK collision operator[4]:

$$Q[f] = \mathcal{M}[f] - f$$

where $\mathcal{M}[f](t,x,v) = \frac{n}{(2\pi T)^{3/2}} e^{-\frac{|v-u|^2}{2T}}$ with

$$n(t,x) = \int_{\mathbb{R}^3} f \mathrm{d}v, \qquad nu(t,x) = \int_{\mathbb{R}^3} f v \mathrm{d}v,$$

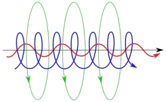
$$n\left(\frac{|u|^2}{2} + \frac{3}{2}T\right)(t,x) = \int_{\mathbb{R}^3} f \frac{|v|^2}{2} \mathrm{d}v.$$

- τ the Knudsen number ($\tau \gg 1$ few collisions, $\tau \ll 1$ many collisions).

[4]Remark: Fokker-Planck-Landau in [Bostan, Finot 2019]

Presentation of the model - finite Larmor radius regime

- B does not depend on t, is space-homogeneous and oriented along the x_3-direction only: $B = (0, 0, b)$,



- perpendicular dynamics time scale is smaller than the parallel one,
- a rescaling gives

$$\partial_t f + \frac{1}{\varepsilon}(v_1 \partial_{x_1} f + v_2 \partial_{x_2} f) + v_3 \partial_{x_3} f + E \cdot \nabla_v f + \frac{1}{\varepsilon}(v_2 \partial_{v_1} f - v_1 \partial_{v_2} f) = \frac{1}{\tau} Q[f],$$

with ε the scaled cyclotronic period.

Multiscale model

$$\partial_t f + \frac{1}{\varepsilon}\left(v_1 \partial_{x_1} f + v_2 \partial_{x_2} f\right) + v_3 \partial_{x_3} f + E \cdot \nabla_v f + \frac{1}{\varepsilon}\left(v_2 \partial_{v_1} f - v_1 \partial_{v_2} f\right) = \frac{1}{\tau} Q[f]$$

$$\Longleftrightarrow$$

$$\partial_t f + \frac{1}{\varepsilon} A z \cdot \nabla_z f + h(t,z) \cdot \nabla_z f = \frac{1}{\tau} Q[f], \quad \text{with } z = (x, v).$$

- Red: fast and periodic scale in the perpendicular plane (x_1, x_2).
- Blue: slow scale in the parallel direction x_3.
- Magenta: collisional scale.

Three asymptotics are considered:

- fluid: fixed $\varepsilon > 0$, $\tau \to 0$,
- gyrokinetic: $\varepsilon \to 0$, fixed $\tau > 0$,
- gyrofluid: ε and $\tau \to 0$, $\varepsilon < \tau$.

Fluid asymptotic: fixed $\varepsilon > 0$, $\tau \to 0$

We get a classical hydrodynamic limit:

- f converges toward a thermodynamical equilibrium given by the Gaussian function $\mathcal{M}[f](t, x, v)$,
- this provides a closure condition for equations on the moments of f associated to 5 collisional invariants,
- the limit model is the classical 3D-Euler system.

Gyrokinetic asymptotic: $\varepsilon \to 0$, fixed $\tau > 0$

We get a highly oscillatory limit:

- strong magnetic field $B = \left(0, 0, \frac{1}{\varepsilon}\right)$ leads to fast oscillations,
- change of variable to filter out the main oscillation: $Z = e^{-\frac{t}{\varepsilon}A} z$, so that $F(t, Z) = f(t, z)$ is solution to

$$\partial_t F + h_{filt}(t, t/\varepsilon, Z) \cdot \nabla_Z F = \frac{1}{\tau} Q_{filt}[F](t, t/\varepsilon, Z),$$

- average with respect to the fast time variable t/ε (considering $\langle \star \rangle = \frac{1}{2\pi} \int_0^{2\pi} \star(t, s, Z) \mathrm{d}s$):

$$\partial_t F + \langle h_{filt} \rangle (t, Z) \cdot \nabla_Z F = \frac{1}{\tau} \langle Q_{filt} \rangle [F](t, Z),$$

- we obtain a collisional Vlasov equation in filtered variables.

Gyrofluid asymptotic: first $\varepsilon \to 0$, then $\tau \to 0$

Collision operator in the gyrokinetic model:

$$\langle Q_{filt} \rangle [F](t, Z) = \frac{1}{2\pi} \int_0^{2\pi} Q_{filt}[F](t, s, Z) \mathrm{d}s.$$

- when $\tau \to 0$, F converges toward an equilibrium of $\langle Q_{filt} \rangle$ called a gyromaxwellian $\mathcal{G}[F]$,

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- when $\tau \to 0$, F converges toward an equilibrium of $\langle Q_{filt}\rangle$ called a gyromaxwellian $\mathcal{G}[F]$,

  $$\mathcal{G}[F](\bar{X},X_3,V) = n\mathcal{M}^2_{\frac{\mu\theta}{\mu-\theta}}(\bar{V}-\bar{U})\mathcal{M}^1_\theta(V_3-U_3)\mathcal{M}^2_\mu(\bar{X}+^\perp\bar{V}-\bar{Y}),$$

  where $\bar{X} = (X_1, X_2)$, $\bar{V} = (V_1, V_2)$,
  $\mathcal{M}^d_T(v) = (2\pi T)^{-d/2}\exp(-\frac{|v|^2}{2T})$,
  $n(X_3) \in \mathbb{R}_+$, $U(X_3) \in \mathbb{R}^3$, $\bar{Y}(X_3) \in \mathbb{R}^2$, $\theta(X_3) \in \mathbb{R}^+$ and $\mu(X_3) \in \mathbb{R}_+$ are (gyro-)moments defined by integrating F against the 8 collisional invariants of $\langle Q_{filt}\rangle[F](t,Z)$.

Gyrofluid asymptotic: first $\varepsilon \to 0$, then $\tau \to 0$

Collision operator in the gyrokinetic model:

$$\langle Q_{filt} \rangle [F](t, Z) = \frac{1}{2\pi} \int_0^{2\pi} Q_{filt}[F](t, s, Z) \mathrm{d}s.$$

- when $\tau \to 0$, F converges toward an equilibrium of $\langle Q_{filt} \rangle$ called a gyromaxwellian $\mathcal{G}[F]$,
- in [Bostan, Finot 2019]: study of its 8 invariants, closure relation for (gyro-)moments of F,
- the limit model is a system of 1D (in X_3) Euler-like equations,
- important point: $\mathcal{G}[F] \neq \frac{1}{2\pi} \int_0^{2\pi} \mathcal{M}_{filt}[F](t, s, Z) \mathrm{d}s$.

Objectives

Develop numerical schemes for this multiscale problem, which ensures asymptotic properties.

- Uniform Accuracy (UA) in gyrokinetic limit:
  - the accuracy of the scheme does not depend on ε,
  - rich literature especially by Chartier, Crouseilles, Lemou, Méhats, Zhao (several papers since 2015).
- Asymptotic Preserving (AP) in fluid and gyrofluid limit:
  - stable and consistent scheme $\forall \tau$, in particular when $\tau \to 0$,
  - rich literature in the fluid hydrodynamic limit, for example [Jin 1999], [Filbet, Jin 2011], [Dimarco, Pareschi 2011], [Lemou, Mieussens 2008], [Coron, Perthame 1991], [C., Crouseilles, Lemou 2012],
  - for two combined limits, the literature is less abundant: [Li, Lu 2017], [Crouseilles, Dimarco, Vignal 2016].

Tools

Use efficient ideas from the literature:

- PIC method for the 6D phase-space semi-discretization, leading to a multiscale set of ODEs,
- scale-separation strategy[5] (new variable s) + spectral method on s,
- exponential integrator on t to get UA property in the gyrokinetic limit $\varepsilon \to 0$,
- implicit scheme on weights to get AP property in the fluid limit $\tau \to 0$,
- penalization method[6,7] to get AP property in the gyrofluid limit $\varepsilon \to 0$ then $\tau \to 0$.

[5] P. Chartier, N. Crouseilles, M. Lemou, F. Méhats, *Numerische Mathematik*, 2015

[6] F. Filbet, S. Jin, *Journal of Computational Physics*, 2010

[7] G. Dimarco, L. Pareschi, *SIAM Journal on Numerical Analysis*, 2011

PIC method for f

Considering N_p macro-particles, of position $x_p(t)$, velocity $v_p(t)$ and weight $\omega_p(t)$, $1 \leq p \leq N_p$, we approximate

$$f(t,z) \approx f_{N_p}(t,z) = \sum_{p=1}^{N_p} \omega_p(t)\delta(z - z_p(t)), \quad \text{with } z_p = (x_p, v_p),$$

and initialization $z_p(0) = z_{p,0}$, $\omega_p(0) = f(0, z_p(0))V_{N_p}$.

- Transport part: inserting it in the Vlasov equation and integrating gives

$$\dot{z}_p(t) = \frac{1}{\varepsilon} A z_p(t) + h(t, z_p(t)), \quad 1 \leq p \leq N_p,$$

- collisional part: weights evolve taking into account collisions

$$\dot{\omega}_p(t) = \frac{1}{\tau}(m_p(t) - \omega_p(t)), \quad 1 \leq p \leq N_p,$$

  where m_p are weights associated to $\mathcal{M}[f_{N_p}]$ after reconstruction of moments.

PIC method in the filtered variables

As in the continuous case, the main oscillation is filtered out:

- change of variable $Z_p(t) = e^{-\frac{t}{\varepsilon}A} z_p(t)$ gives

$$\dot{Z}_p(t) = h_{filt}(t, t/\varepsilon, Z_p(t)), \quad 1 \leq p \leq N_p,$$

- compute $m_p(t) = \mathcal{M}_{filt}[F_{N_p}](t, t/\varepsilon, Z_p(t)) V_{N_p}$ after reconstructing the moments of F_{N_p},
- same equation on weights:

$$\dot{\omega}_p(t) = \frac{1}{\tau}(m_p(t) - \omega_p(t)), \quad 1 \leq p \leq N_p.$$

Scale-separation strategy

- Consider the slow time scale t and the fast periodic time scale $s = t/\varepsilon$ as independent,
- introduce double-scale quantities $\mathcal{Z}_p(t,s)$ and $\mathcal{W}_p(t,s)$ satisfying

$$\mathcal{Z}_p(t, t/\varepsilon) = Z_p(t), \quad \mathcal{W}_p(t, t/\varepsilon) = \omega_p(t),$$

- additional variable gives a degree of freedom,
- use it to bound the time derivatives of $\mathcal{Z}$ uniformly in ε: well prepared initial data.

Spectral method on s and exponential integrator in t

Let focus on transport equation (same strategy on weights)

$$\partial_t \mathcal{Z}_p(t,s) + \frac{1}{\varepsilon}\partial_s \mathcal{Z}_p(t,s) = \mathcal{H}_p(t,s),$$

where $\mathcal{H}_p(t,s) = h_{filt}(t,s,\mathcal{Z}_p(t,s))$.

- Fourier transform gives equations for modes

$$\frac{d}{dt}\hat{\mathcal{Z}}_{p,l}(t) + \frac{il}{\varepsilon}\hat{\mathcal{Z}}_{p,l}(t) = \hat{\mathcal{H}}_{p,l}(t),$$

- multiply by $e^{\frac{il}{\varepsilon}t}$ and integrate between two times t^n and $t^{n+1} = t^n + \Delta t$:

$$\hat{\mathcal{Z}}_{p,l}(t^{n+1}) = e^{-\frac{il}{\varepsilon}\Delta t}\hat{\mathcal{Z}}_{p,l}(t^n) + \int_{t^n}^{t^{n+1}} e^{-\frac{il}{\varepsilon}(t^{n+1}-t)}\hat{\mathcal{H}}_{p,l}(t)\mathrm{d}t,$$

- approximate $\hat{\mathcal{H}}_{p,l}(t)$ by $\hat{\mathcal{H}}_{p,l}(t^n)$ to get a first order[8] scheme

$$\hat{\mathcal{Z}}_{p,l}^{n+1} = e^{-\frac{il}{\varepsilon}\Delta t}\hat{\mathcal{Z}}_{p,l}^{n} + \frac{\varepsilon}{il}\left(1 - e^{-\frac{il}{\varepsilon}\Delta t}\right)\hat{\mathcal{H}}_{p,l}^{n},$$

- reconstruct the truncated Fourier series:

$$\mathcal{Z}_p^n(s) = \sum_{l=-N_s/2}^{N_s/2-1} \hat{\mathcal{Z}}_{p,l}^n e^{ils},$$

- evaluate it on the diagonal $s = t^n/\varepsilon$: $Z_p^n = \mathcal{Z}_p^n\left(\frac{t^n}{\varepsilon}\right)$ and apply the inverse change of variable $z_p^n = e^{\frac{t^n}{\varepsilon}A} Z_p^n$.

[8]Remark: in practice we used a 2nd-order scheme as well.

Asymptotic behaviour of scheme A

Recall equations on Fourier modes

$$\frac{d}{dt}\hat{\mathcal{Z}}_{p,l}(t) + \frac{il}{\varepsilon}\hat{\mathcal{Z}}_{p,l}(t) = \hat{\mathcal{H}}_{p,l}(t),$$
$$\frac{d}{dt}\hat{\mathcal{W}}_{p,l}(t) + \frac{il}{\varepsilon}\hat{\mathcal{W}}_{p,l}(t) = \frac{1}{\tau}\left(\hat{\mathcal{M}}_{p,l}(t) - \hat{\mathcal{W}}_{p,l}(t)\right).$$

Scheme A given by

$$\hat{\mathcal{Z}}^{n+1}_{p,l} = e^{-\frac{il}{\varepsilon}\Delta t}\hat{\mathcal{Z}}^{n}_{p,l} + \frac{\varepsilon}{il}\left(1 - e^{-\frac{il}{\varepsilon}\Delta t}\right)\hat{\mathcal{H}}^{n}_{p,l},$$

$$\hat{\mathcal{W}}^{n+1}_{p,l} = e^{-\left(\frac{il}{\varepsilon}+\frac{1}{\tau}\right)\Delta t}\hat{\mathcal{W}}^{n}_{p,l} + \frac{\varepsilon}{il\tau+\varepsilon}\left(1 - e^{-\left(\frac{il}{\varepsilon}+\frac{1}{\tau}\right)\Delta t}\right)\hat{\mathcal{M}}^{\star}_{p,l},$$

- is UA in the gyrokinetic limit ($\varepsilon \to 0$, fixed $\tau > 0$), if we take constant initial datas $\mathcal{Z}_p(0,s) = Z_p(0)$, $\mathcal{W}_p(0,s) = \omega_p(0)$[9],

[9] Remark: more elaborate well prepared initial datas are needed for the 2nd-order scheme.

Asymptotic behaviour of scheme A

Recall equations on Fourier modes

$$\frac{d}{dt}\hat{\mathcal{Z}}_{p,l}(t) + \frac{il}{\varepsilon}\hat{\mathcal{Z}}_{p,l}(t) = \hat{\mathcal{H}}_{p,l}(t),$$
$$\frac{d}{dt}\hat{\mathcal{W}}_{p,l}(t) + \frac{il}{\varepsilon}\hat{\mathcal{W}}_{p,l}(t) = \frac{1}{\tau}\left(\hat{\mathcal{M}}_{p,l}(t) - \hat{\mathcal{W}}_{p,l}(t)\right).$$

Scheme A given by

$$\hat{\mathcal{Z}}_{p,l}^{n+1} = e^{-\frac{il}{\varepsilon}\Delta t}\hat{\mathcal{Z}}_{p,l}^{n} + \frac{\varepsilon}{il}\left(1 - e^{-\frac{il}{\varepsilon}\Delta t}\right)\hat{\mathcal{H}}_{p,l}^{n},$$

$$\hat{\mathcal{W}}_{p,l}^{n+1} = e^{-\left(\frac{il}{\varepsilon}+\frac{1}{\tau}\right)\Delta t}\hat{\mathcal{W}}_{p,l}^{n} + \frac{\varepsilon}{il\tau+\varepsilon}\left(1 - e^{-\left(\frac{il}{\varepsilon}+\frac{1}{\tau}\right)\Delta t}\right)\hat{\mathcal{M}}_{p,l}^{\star},$$

- is AP in the fluid limit ($\tau \to 0$, fixed $\varepsilon > 0$), if we consider $\hat{\mathcal{M}}_{p,l}^{\star}$ "semi-implicit" (computed from $\mathcal{Z}_p^{n+1}$ and $\mathcal{W}_p^{n}$), remark: UA if $\mathcal{M}$ does not depend on weights $\mathcal{W}$.

Penalization approach

- In the gyrofluid limit ($\varepsilon \to 0$ then $\tau \to 0$), equilibrium of collision operator $\langle Q_{filt} \rangle[F]$ is $\mathcal{G}[F] \neq \langle \mathcal{M}_{filt}[F] \rangle$,
- we will enforce the right asymptotic behaviour by modifying weights scheme, starting from

$$\partial_t \mathcal{W}_p + \frac{1}{\varepsilon} \partial_s \mathcal{W}_p = \frac{1}{\tau}(\mathcal{M}_p - \mathcal{W}_p) - \frac{1}{\tau}\mathcal{G}_p + \frac{1}{\tau}\mathcal{G}_p,$$

- Fourier transform in s + integration on $[t^n, t^{n+1}]$ but different quadratures on

$$\frac{1}{\tau} \int_{t^n}^{t^{n+1}} e^{-\left(\frac{il}{\varepsilon} + \frac{1}{\tau}\right)(t^{n+1}-t)} (\hat{\mathcal{M}}_{p,l}(t) - \hat{\mathcal{G}}_{p,l}(t)) \mathrm{d}t$$

and

$$\frac{1}{\tau} \int_{t^n}^{t^{n+1}} e^{-\left(\frac{il}{\varepsilon} + \frac{1}{\tau}\right)(t^{n+1}-t)} \hat{\mathcal{G}}_{p,l}(t) \mathrm{d}t,$$

- for asymptotics in $\varepsilon \to 0$, we focus on mode 0.

Asymptotic behaviour of scheme B

Scheme B whose mode 0 is given by

$$\hat{\mathcal{Z}}_{p,0}^{n+1} = \hat{\mathcal{Z}}_{p,0}^{n} + \Delta t \hat{\mathcal{H}}_{p,0}^{n},$$

$$\hat{\mathcal{W}}_{p,0}^{n+1} = e^{-\frac{\Delta t}{\tau}} \hat{\mathcal{W}}_{p,0}^{n} + \frac{\Delta t}{\tau} e^{-\frac{\Delta t}{\tau}} \left(\hat{\mathcal{M}}_{p,0}^{n} - \hat{\mathcal{G}}_{p,0}^{n} \right) + \left(1 - e^{-\frac{\Delta t}{\tau}} \right) \hat{\mathcal{G}}_{p,0}^{n+1},$$

- is AP in the gyrofluid limit ($\varepsilon \to 0$ then $\tau \to 0$),
- is AP in the gyrokinetic limit ($\varepsilon \to 0$, fixed $\tau > 0$).

But

- we lose the right behaviour in the fluid limit...
- We can propose a convex combination of schemes A and B:

$$\hat{\mathcal{W}}_{p,l}^{n+1} = \frac{\varepsilon}{\tau + \varepsilon} \hat{\mathcal{W}}_{p,l}^{n+1,A} + \left(1 - \frac{\varepsilon}{\tau + \varepsilon} \right) \hat{\mathcal{W}}_{p,l}^{n+1,B}.$$

One-particle test: multiscale ODE framework

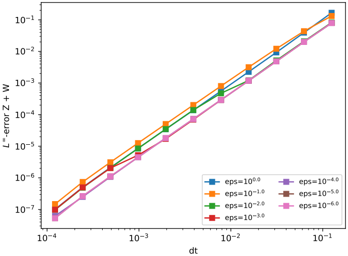
$$\dot{z}(t) = \frac{1}{\varepsilon} A z(t) + h(t, z),$$
$$\dot{\omega}(t) = \frac{1}{\tau}(\mathcal{M}(\omega, z) - \omega(t)),$$

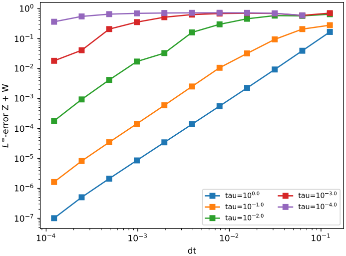
with

- $E(t, x) = ((x_1 + x_3)\cos(t), x_1 x_2 \sin(t), -x_2^2 e^{-t^2})$,
- $z(0) = (1, 1, 0, 1/2, 1/2, 3/2)$, $\omega(0) = 1$.

We plot $||z\text{-error}||_{L^\infty} + ||\omega\text{-error}||_{L^\infty}$ as a function of Δt, error compared to a reference solution.

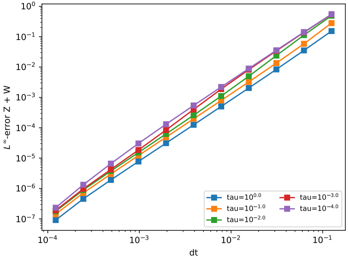
One-particle test: $\mathcal{M}(\omega, z) = 1 + |z|^2 + e^{-\omega^2}$





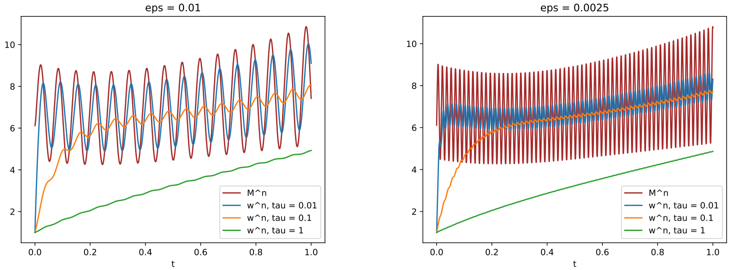
2nd-order scheme.
Left: L^∞-Error for $\tau = 1$ and different ε; UA in gyrokinetic limit.
Right: L^∞-Error for $\varepsilon = 1$ and different τ; AP in fluid limit.

One-particle test: $\mathcal{M}(\omega, z) = \mathcal{M}(z) = 1 + |z|^2$



2nd-order scheme.
L^∞-Error for $\varepsilon = 1$ and different τ; UA in fluid limit.

One-particle test: time history of $\mathcal{M}(z(t))$ and $\omega(t)$

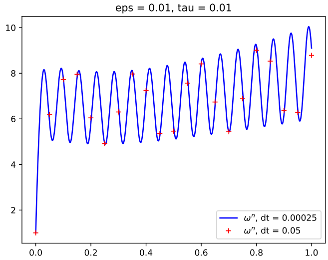


Fluid limit: for fixed $\varepsilon > 0$, $w(t)$ converges toward $\mathcal{M}(z(t))$ when $\tau \to 0$.

Gyrokinetic limit: for fixed $\tau > 0$, $w(t)$ converges toward the average of $\mathcal{M}(z(t))$ when $\varepsilon \to 0$.

$\Delta t = 2.5 \times 10^{-4}$ in both cases.

One-particle test: time history of $\omega(t)$, $\mathcal{M}(z)$-case



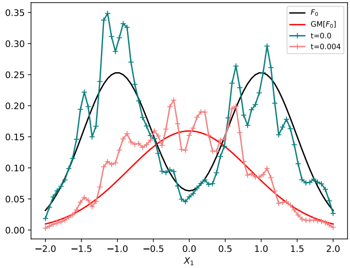
UA: scheme captures the strong relaxation and the highly oscillatory behaviour, without resolving these two stiffnesses ($\Delta t > \varepsilon = \tau$).

PDE framework: gyrofluid limit

We consider the simplified filtered model

$$\partial_t F = \frac{1}{\tau} Q_{filt}[F] = \frac{1}{\tau}(\mathcal{M}_{filt}[F] - F).$$

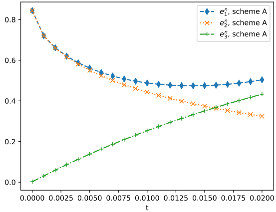
We plot (a slice of) the particles density initially and at time 4×10^{-3}, as well as the gyromaxwellian equilibrium.

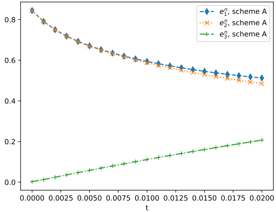


PDE framework: error study of scheme A

We plot 3 errors: $e_1^n = \sum_p |\omega_p^n - \mathcal{G}_p^{ex}|$, $e_2^n = \sum_p |\omega_p^n - \mathcal{G}_p^n|$ and $e_3^n = \sum_p |\mathcal{G}_p^n - \mathcal{G}_p^{ex}|$.

Parameters: $N_p = 12288000$, $\varepsilon = 10^{-8}$, $\Delta t = 10^{-3}$, $N_s = 4$, $\Delta x \approx 0.37$, $\tau = 10^{-4}$ (left) and $\tau = 2 \times 10^{-3}$ (right).



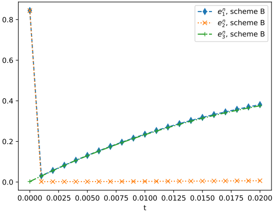


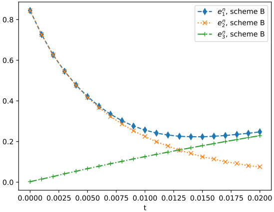
e_3^n increases since gyromoments are not conserved exactly (and it deteriorates $\mathcal{G}_p^n$). Better if N_p increases.
e_2^n big since scheme A is not AP in the gyrofluid limit.

PDE framework: error study of scheme B

We plot 3 errors: $e_1^n = \sum_p |\omega_p^n - \mathcal{G}_p^{ex}|$, $e_2^n = \sum_p |\omega_p^n - \mathcal{G}_p^n|$ and $e_3^n = \sum_p |\mathcal{G}_p^n - \mathcal{G}_p^{ex}|$.

Parameters: $N_p = 12288000$, $\varepsilon = 10^{-8}$, $\Delta t = 10^{-3}$, $N_s = 4$, $\Delta x \approx 0.37$, $\tau = 10^{-4}$ (left) and $\tau = 2 \times 10^{-3}$ (right).





e_3^n increases since gyromoments are not conserved exactly (and it deteriorates $\mathcal{G}_p^n$). Better if N_p increases.
e_2^n small since scheme B is AP in the gyrofluid limit.

Conclusion and opening

- Two schemes were developed for a 3Dx-3Dv multiscale Vlasov equation involving collisions and fast oscillations.
- Asymptotic properties (UA or AP) are obtained (proofs in the submitted paper and numerical investigations) for three limits.

- A projection technique (as in [Dimarco, Loubère 2013] or [Gamba, Tharkabhushanam 2009]) could ensure preservation of gyromoments.
- Micro-macro approach to reduce computational time.
- Coupling with Maxwell equations for a self-consistent electromagnetic field.

Merci pour votre attention !